



NEUROPROSTHETICS FOR RESTORATION OF UPPER LIMB FUNCTION

Jennifer Collinger October 18, 2014

Email: collingr@pitt.edu

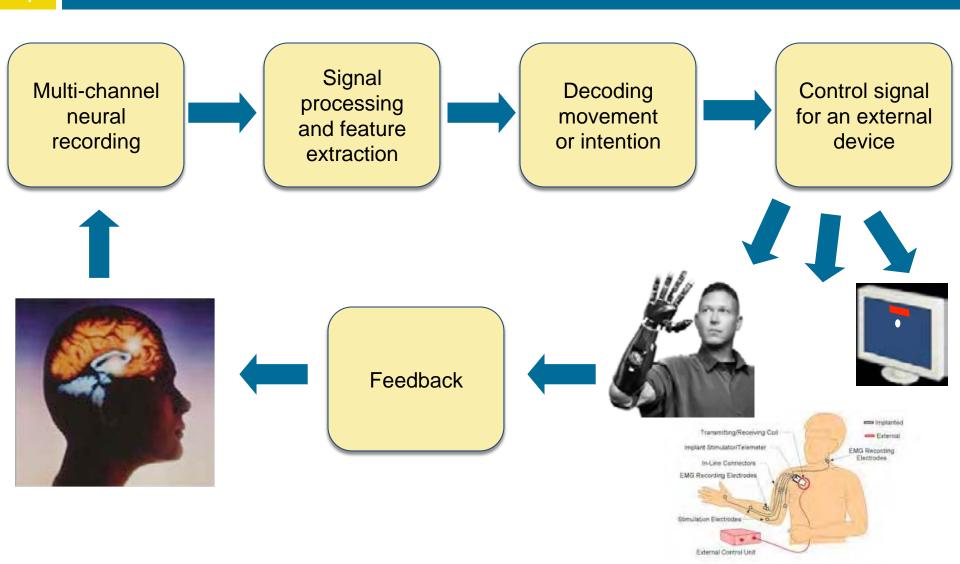
Motivation

- People with severe disabilities may have limited means to communicate or interact with their environment
- Traditional assistive technologies often require some amount of dexterity to operate
- A brain-computer interface (BCI) can establish a direct link between the brain and an external device
 - Potential for high degree-of-freedom, intuitive control
 - Rehabilitation

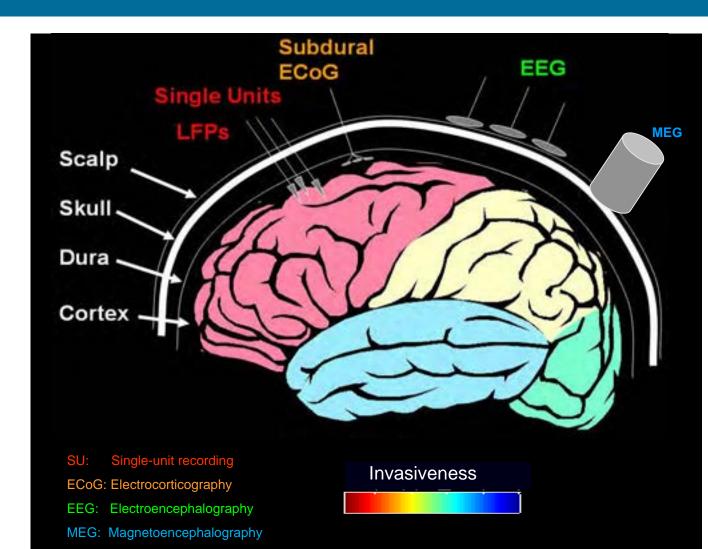
Outline

- Definition of BCI/ neuroprosthesis
- Multidisciplinary research approach
- BCI for neurorehabilitation
- □ BCI as assistive technology
 - User Priorities
 - Clinical research at Pittsburgh
- Barriers to clinical translation

Brain-computer interfaces (BCI)



Neural Signal Acquisition Methods

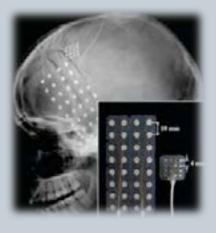


Clinical BCI Research in Pittsburgh

Magnetoencephalography (MEG)



Electrocorticography (ECoG)

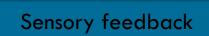


Intracortical microelectrodes



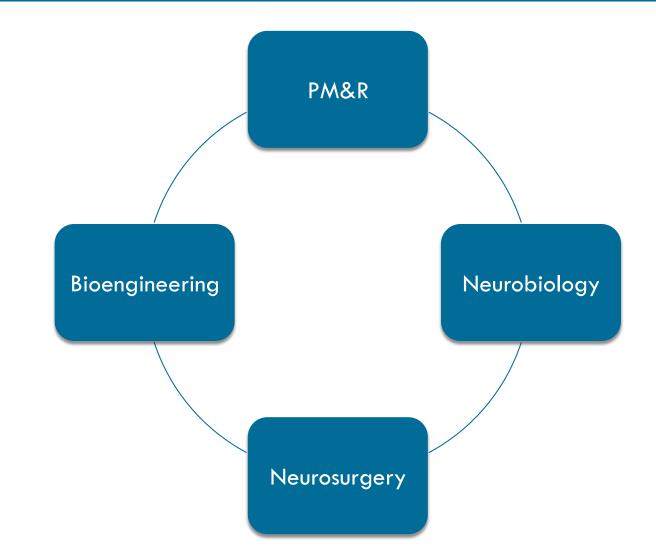


Motor command

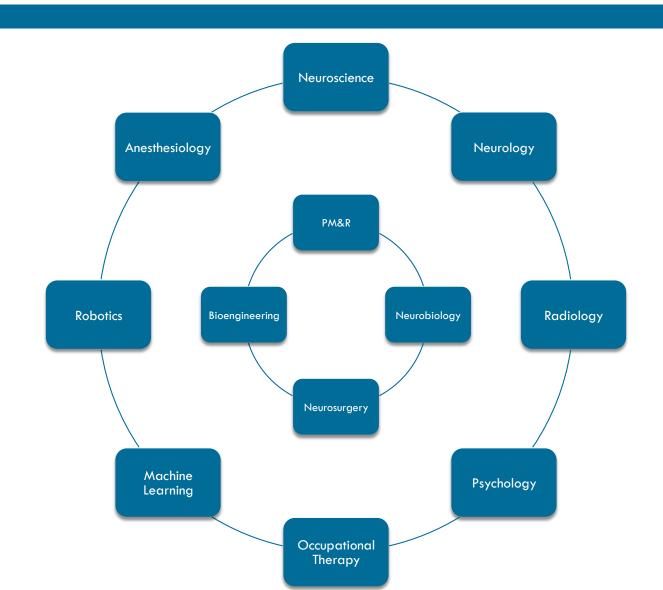




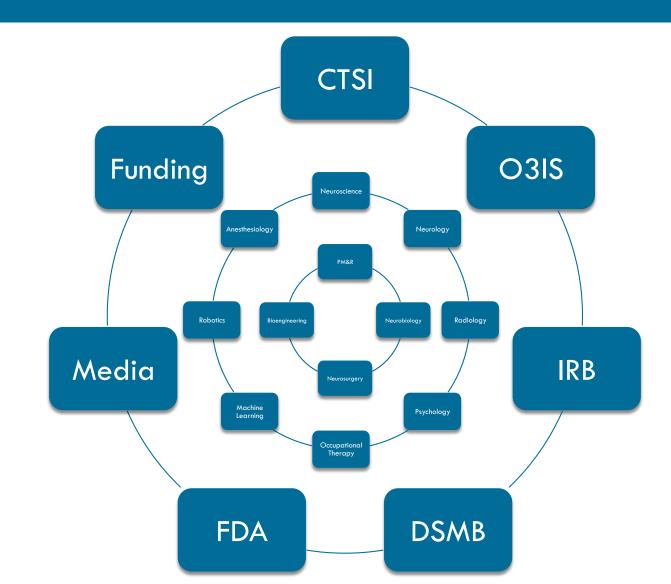
Multidisciplinary team



Multidisciplinary team



Multidisciplinary team



Collaborative Approach in the Development of High-Performance Brain–Computer Interfaces for a Neuroprosthetic Arm: Translation from Animal Models to Human Control

Jennifer L. Collinger, Ph.D.^{1–3}, Michael A. Kryger, M.D., M.S.², Richard Barbara, Ph.D.^{2,*}, Timothy Betler, M.A.^{4,*}, Kristen Bowsher, Ph.D.^{5,*}, Elke H. P. Brown, M.D.^{2,*}, Samuel T. Clanton, Ph.D.^{2,*}, Alan D. Degenhart, B.S.^{3,6,*}, Stephen T. Foldes, Ph.D.^{1,2,6,*}, Robert A. Gaunt, Ph.D.^{2,3,*}, Ferenc E. Gyulai, M.D.^{7,*}, Elizabeth A. Harchick, B.S.^{2,*}, Deborah Harrington, B.S.^{2,*}, John B. Helder, M.S.^{8,*}, Timothy Hemmes^{*}, Matthew S. Johannes, Ph.D.^{8,*}, Kapil D. Katyal, M.S.^{8,*}, Geoffrey S. F. Ling, M.D., Ph.D., F.A.A.N.^{9,*}, Angus J. C. McMorland, Ph.D.^{10,11,*}, Karina Palko, B.S.^{*}, Matthew P. Para, M.E.^{8,*}, Janet Scheuermann, B.A.^{*}, Andrew B. Schwartz, Ph.D.^{2,3,6,10–12,*}, Elizabeth R. Skidmore, Ph.D., O.T.R./L.^{2,13,*}, Florian Solzbacher, Ph.D.^{14–16,*}, Anita V. Srikameswaran, M.D.^{4,*}, Dennis P. Swanson, R.Ph., M.S.^{17,*}, Scott Swetz, M.S.^{8,*}, Elizabeth C. Tyler-Kabara, M.D., Ph.D.^{2,3,12,18,*}, Meel Velliste, Ph.D.^{10,11,*}, Wei Wang, M.D., Ph.D.^{2,3,6,19,*}, Douglas J. Weber, Ph.D.^{1–3,6,*}, Brian Wodlinger, Ph.D.^{2,6,*}, and Michael L. Boninger, M.D.^{1–3,12}

Abstract

Our research group recently demonstrated that a person with tetraplegia could use a brain–computer interface (BCI) to control a sophisticated anthropomorphic robotic arm with skill and speed approaching that of an able-bodied person. This multiyear study exemplifies important principles in translating research from foundational theory and animal experiments into a clinical study. We present a roadmap that may serve as an example for other areas of clinical device research as well as an update on study results. Prior to conducting a multiyear clinical trial, years of animal research preceded BCI testing in an epilepsy monitoring unit, and then in a short-term (28 days) clinical investigation. Scientists and engineers developed the necessary robotic and surgical hardware, software environment, data analysis techniques, and training paradigms. Coordination among researchers, funding institutes, and regulatory bodies ensured that the study would provide valuable scientific information in a safe environment for the study participant. Finally, clinicians from neurosurgery, anesthesiology, physiatry, psychology, and occupational therapy all worked in a multidisciplinary team along with the other researchers to conduct a multiyear BCI clinical study. This teamwork and coordination can be used as a model for others attempting to translate basic science into real-world clinical situations. Clin Trans Sci 2013; Volume **#**: 1–8

Keywords: brain, clinical trials, methodology, translational research

MEG for Neurofeedback

Motor Rehabilitation: SCI

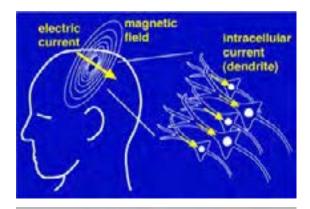
- 12
- □ 225,000-296,000 people in the US with SCI
- Cervical level SCI impairs the ability to grasp and manipulate objects
 - Impacts independence and social participation
 - Improvement of hand function is a top priority for functional recovery
- Traditional rehab involves repetition of movements
 - What if patient cannot voluntarily activate muscles?
 - **\square** Limited improvement ~ 1 year after injury

Definitions

- 13
- Biofeedback: The technique of monitoring physiological functions to provide information about these systems, with the goal of being able to manipulate these signals
- Neurofeedback: A type of biofeedback that uses real-time displays of brain activity, with the goal of controlling CNS activity. Typically, the goal is to "normalize" brain activity.

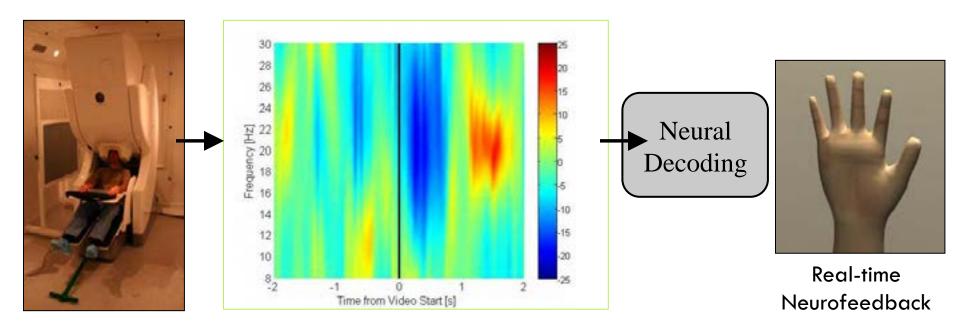
Technology: MEG



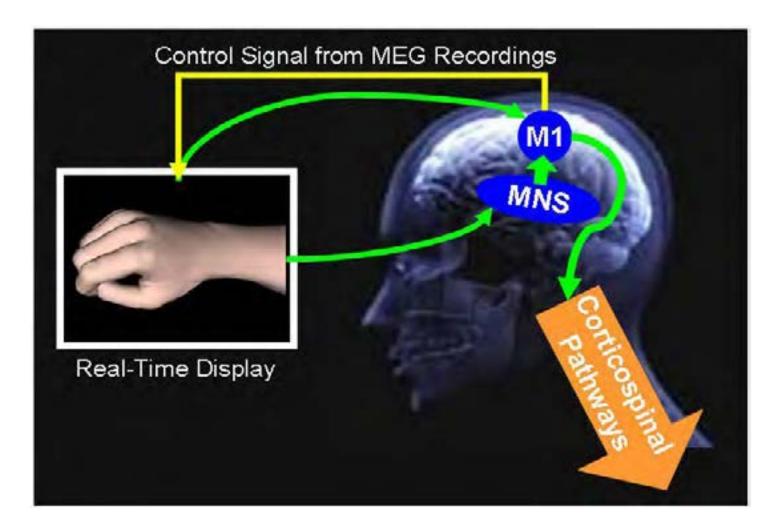




MEG Neurofeedback



Facilitation of Motor Cortex Activation

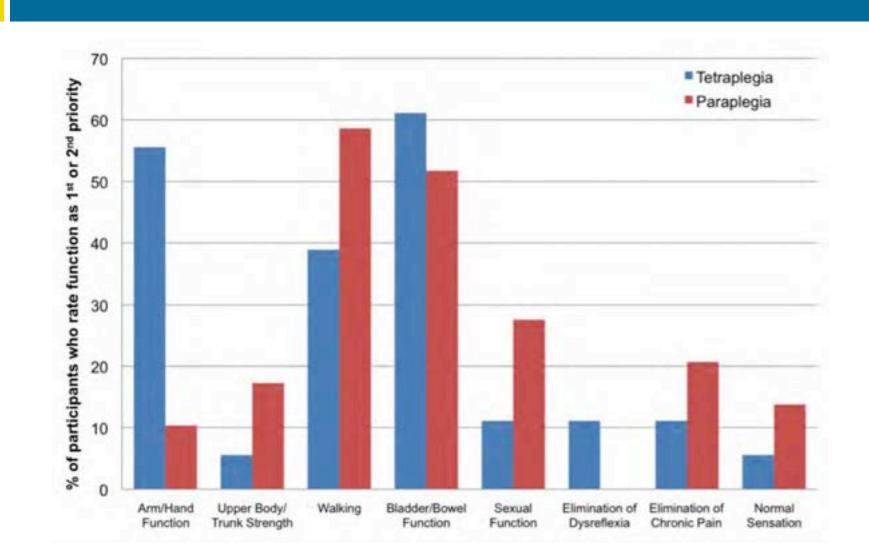


BCI as assistive technology

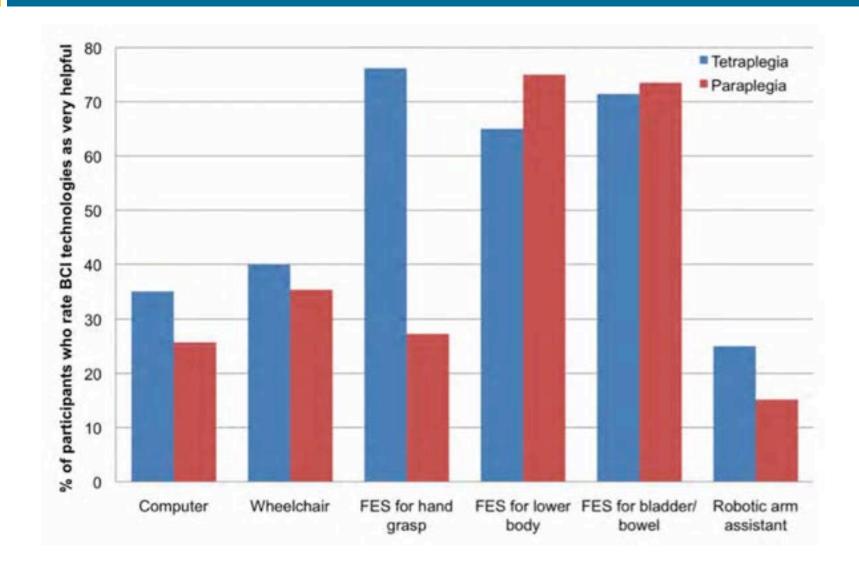
Who are our end users?

- 18
- People with mobility or communication-related impairments whose needs are not met by traditional assistive technology
- Each diagnosis group or specific impairment may desire different functionality
 - Recording modality
 - Risk/benefit tradeoffs
 - Type of terminal device(s)

What do they want?



BCI-controlled assistive technology



BCI design characteristics

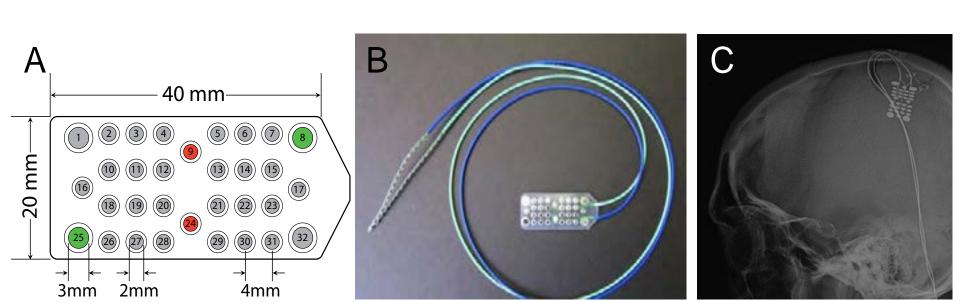
- 21
- Independent operation was most important
- Training time was the least important
- 70% rated non-invasiveness as very important
- More than half would "definitely" or "very likely" consider having surgery to implant BCI electrodes

Priorities for users with ALS

- □ Most important features of a BCI
 - Accuracy, set-up simplicity, standby mode reliability, available functions
- □ EEG vs. implanted electrodes
 - 84% accept electrode cap
 - 72% accept surgical implant (outpatient)
 - 41% accept surgical implant (short hospital stay)
- BCI-controlled assistive technologies
 - Power wheelchair and robot arm control trended towards a more significant interest

ECoG BCI

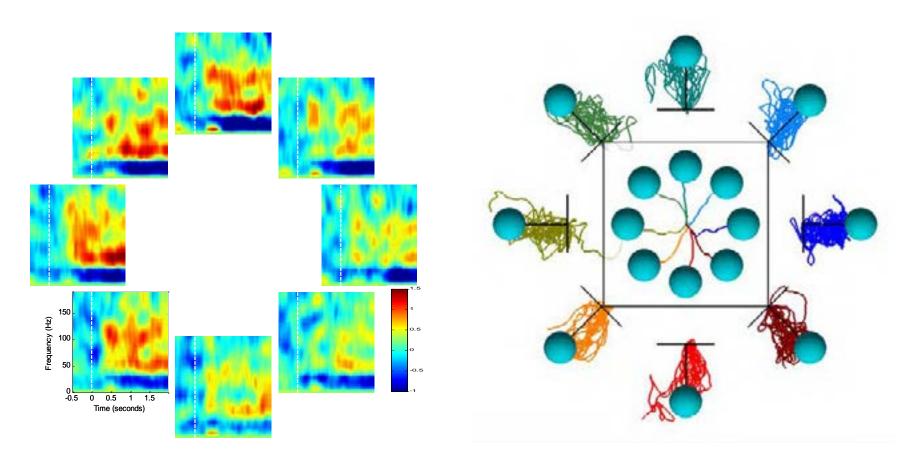
ECoG BCI: First Participant



A short-term study over 28 days (21 testing days)
Subject: 30-year old male, C4-level spinal cord injury

2D Cursor Control

ECoG signal modulation and 2D cursor trajectories



Channel 4

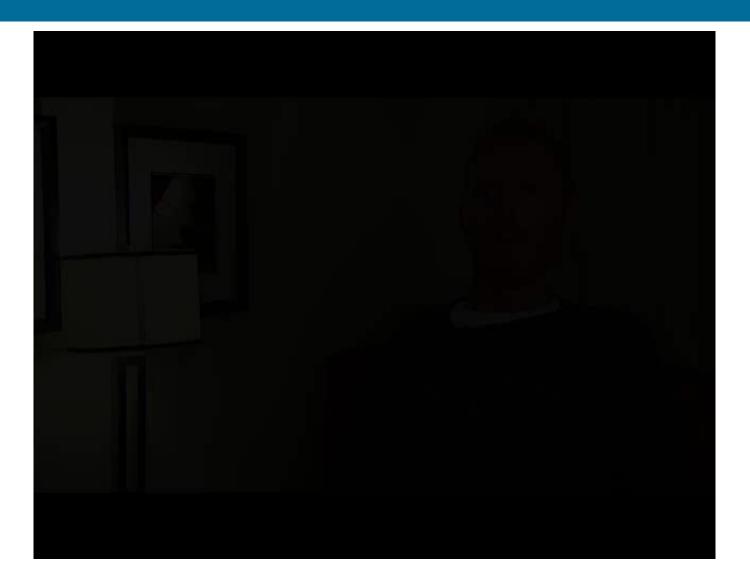
Average success rate: 87% over 176 trials

3D Cursor Control

3D Control of the MPL

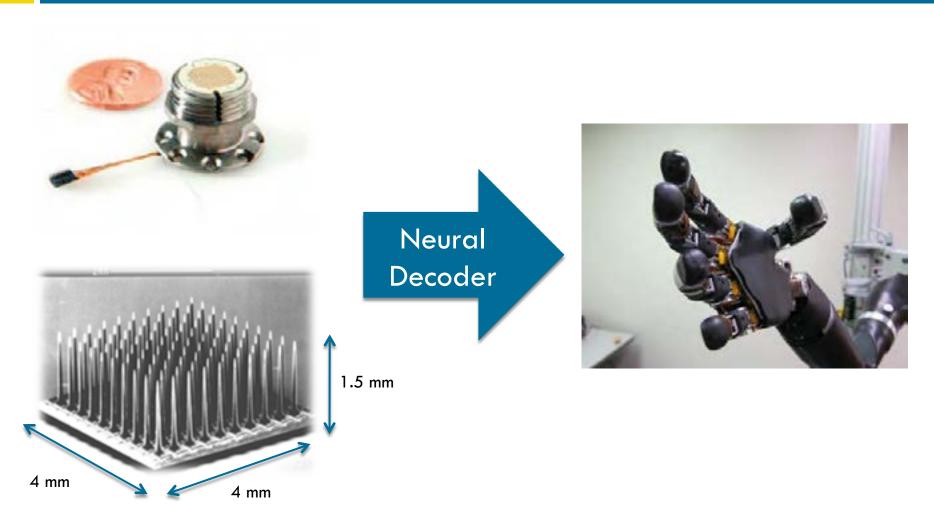


Meet our participant



Intracortical BCI

Intracortical BCI for robotic arm control



Conducted under an FDA Investigational Device Exemption

Collaborators: Device Regulation

Blackrock Microsystems

Johns Hopkins University
Applied Physics Laboratory

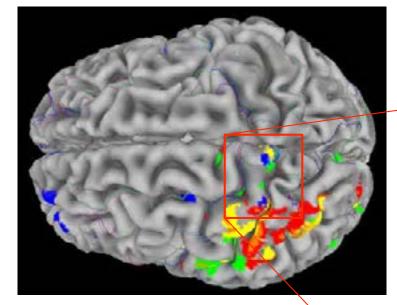




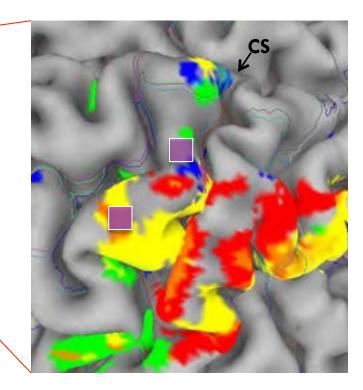
- □ FDA: Investigational Device Exemption
 - Basic science research
 - Clinical protocol development



Presurgical planning

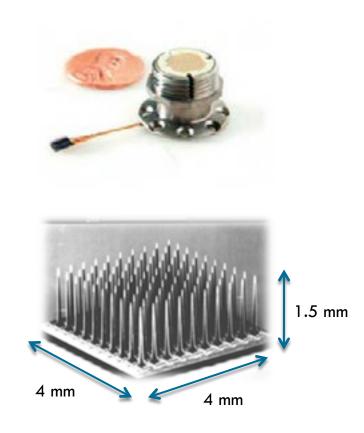


Hand grasp RED Shoulder shrug BLUE Lip pursing GREEN Complex finger YELLOW



Implantation surgery: 2/10/12



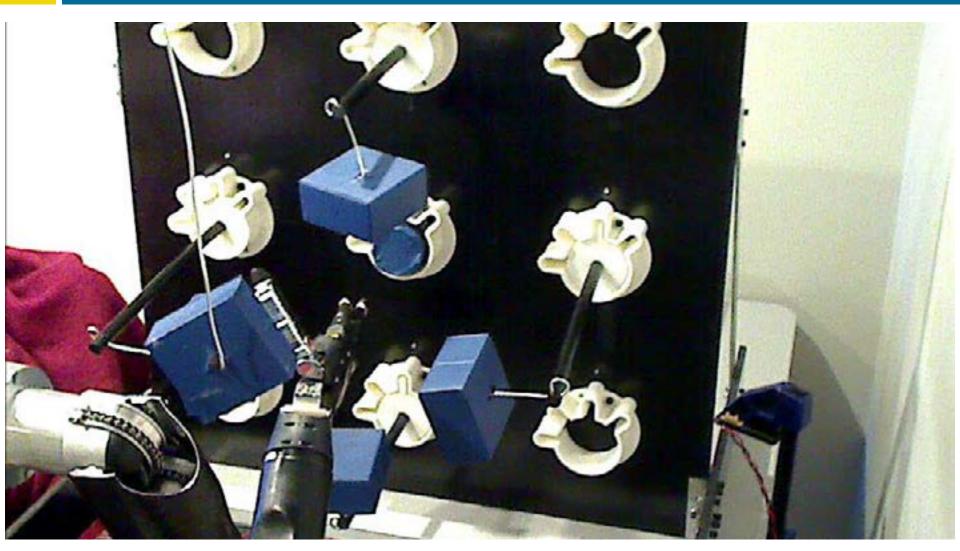


Collaborators: Surgical

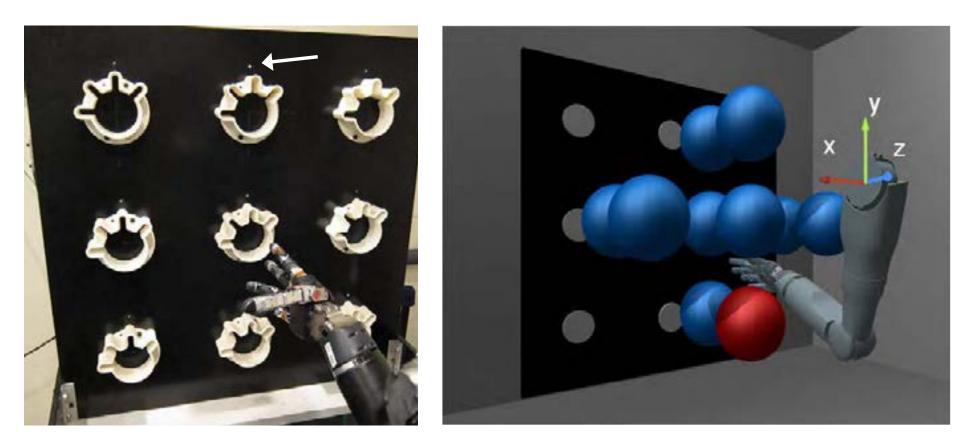
- □ Neurosurgery
 - Minimize risk, ensure device function
- Neurophysiology
 - Array placement
- Anesthesiology
 - Screening for co-morbidities
 - Special considerations
 - tetraplegia, spastic, or flaccid paralysis
 - autonomic hyperreflexia
 - receptor up-or-down regulation at the neuromuscular junction
 - cervical fusions
 - tracheostomy
- Psychology



3D control: 2/21/12



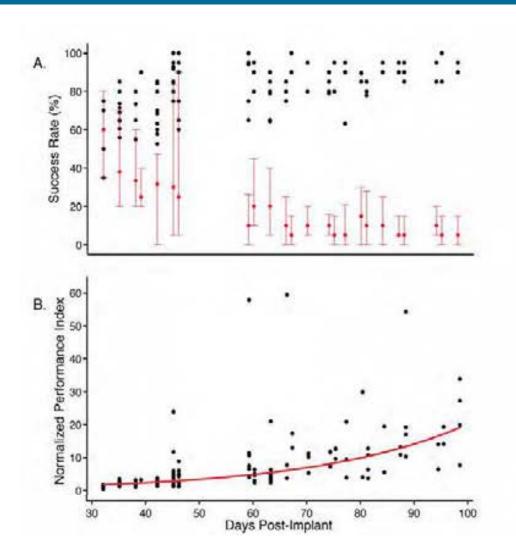
7D sequence task



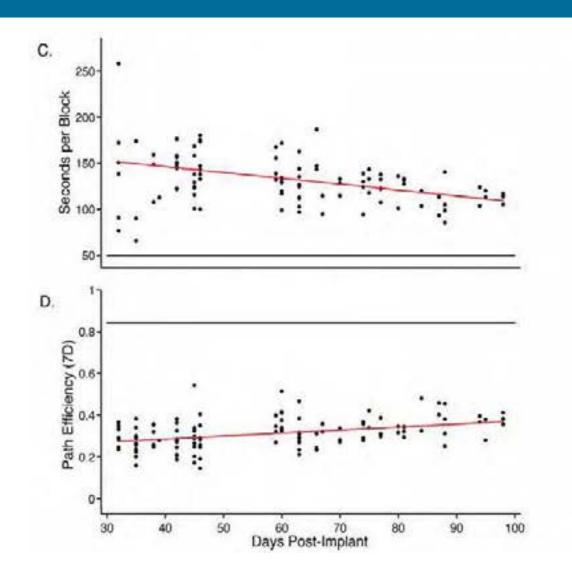
7D sequence task: 5/14/12



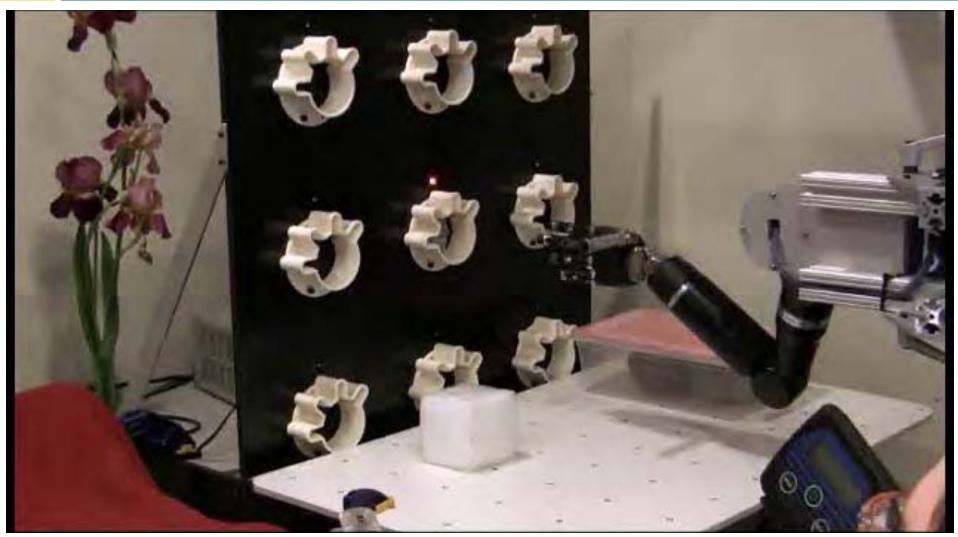
Results: 7D performance



Results: 7D performance



Action Research Arm Test (ARAT)



ARAT Performance

• 9 of 19 possible tasks were evaluated

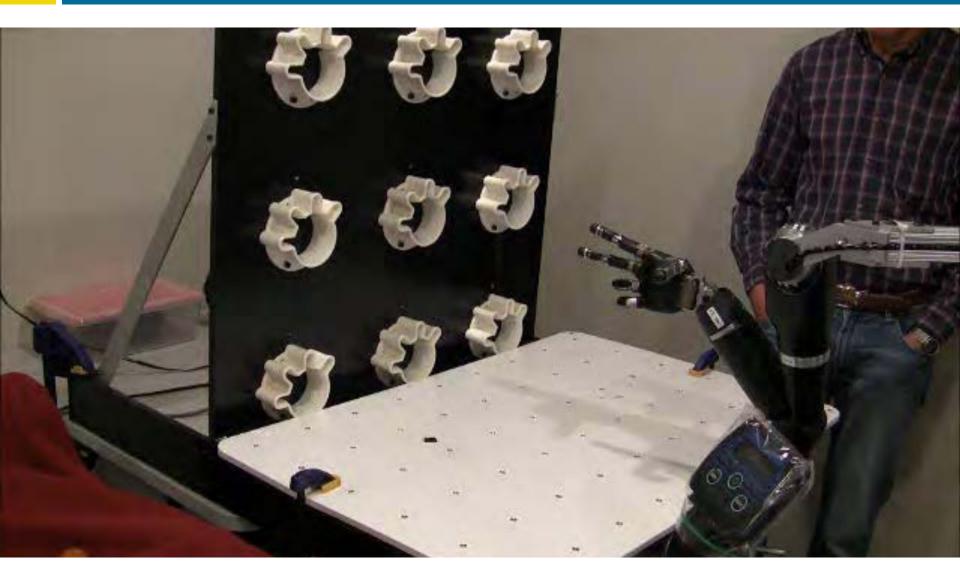


- Each scored from 0-3
- Score ranged from 15-17 (out of 27) with BCI
 - Δ 5.7 points is clinically significant
- Mean completion time ranged from 9.5-21.3 s

Different grasp strategies



Hand shaping (8D control)



Chocolate

Chocolate

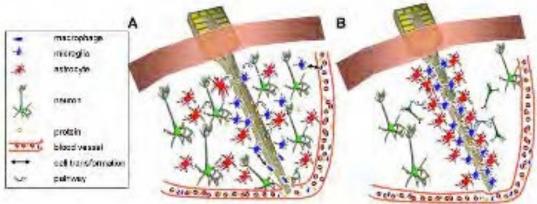
Sensory feedback is crucial for normal motor control



Barriers to Clinical Translation

Recording quality/stability

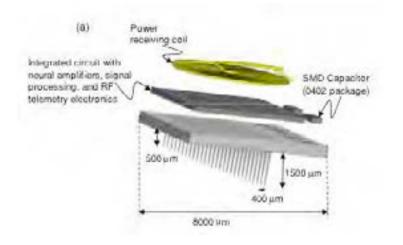
Host/tissue interface

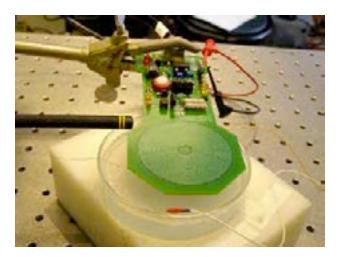


Possible solutions: Electrode geometry, materials, coatings

- Resolution vs. invasiveness tradeoff
- □ Effects of distractions/noise
- Recalibration

Telemetry





How much information is

needed?

• System complexity

- Reduce infection risk
- Data acquisition system

portability?

Independent operation

Integration with other technology

50

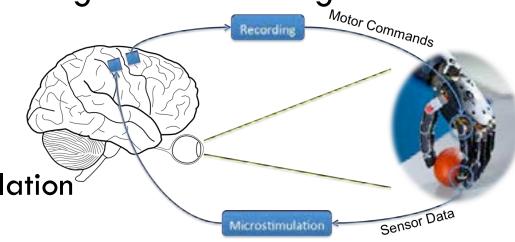




Sensory feedback

Each modality has advantages and challenges

- Visual
- Non-invasive
- Cortical surface
- Intracortical microstimulation
- Optical stimulation
- Peripheral nervous system



Other challenges?

- Meeting performance expectations
- Independent operation or remote monitoring
- Cost
- Clinician and patient education

Summary

- 53
- BCIs have applications for rehabilitation and assistive technology
- An intracortical BCI enabled a participant to perform natural reaching and grasp movements with skill approaching that of an able-bodied individual
- □ Additional work is needed to overcome barriers to clinical translation → multidisciplinary team

Acknowledgments

- Funding
 - DARPA
 - NIH
 - VA
- Faculty collaborators
 - Michael Boninger
 - Andrew Schwartz
 - Rob Gaunt
 - Wei Wang
 - Doug Weber
 - Elizabeth Tyler-Kabara
 - Elizabeth Skidmore
- External collaborators
 - JHU APL
 - Blackrock Microsystems

- Post-docs/students/staff
 - Brian Wodlinger
 - Stephen Foldes
 - Michael Kryger
 - Meel Velliste
 - Angus McMorland
 - Elke Brown
 - John Downey
 - Sharlene Flesher
 - Danielle Rager
 - Alan Degenhart
 - Debbie Harrington
 - Jeff Weiss
 - Max Maguire
- Study participants

Thank you

